

## Lecture 09: Martingales and Azuma's Inequality

# Disclaimer

- This is a very informal treatment of the concept of Martingales
- In particular, the intuitions are specific to discrete spaces
- Inquisitive readers are referred to study  $\sigma$ -algebras for a more formal treatment of this material

# In this Lecture

- Martingales
- Specific to Discrete Sample Spaces
- Specifically, Doob's Martingale
- Azuma's Inequality

- Let  $\Omega$  be a sample space with probability distribution  $p$

## Definition ( $\sigma$ -Field)

A  $\sigma$ -field  $\mathcal{F}$  on  $\Omega$  is a collection of subsets of  $\Omega$  that

- 1 Contains  $\emptyset$  and  $\Omega$ ,
- 2 Is closed under unions, intersections, and complementation.

## Example

- For example  $\mathcal{F}_0 = \{\emptyset, \Omega\}$  is a  $\sigma$ -field
- Suppose  $\Omega = \{0, 1\}^n$
- Let  $\mathcal{F}_1 = \mathcal{F}_0 \cup \{0\{0, 1\}^{n-1}, 1\{0, 1\}^{n-1}\}$ . This is also a  $\sigma$ -field
- Let  $\mathcal{F}_2 = \{S\{0, 1\}^{n-2} : S \subseteq \{00, 01, 10, 11\}\}$ . We use the convention: If  $S = \emptyset$  then  $S\{0, 1\}^{n-2} = \emptyset$ . So,  $\mathcal{F}_2$  has 16 elements, and  $\mathcal{F}_1 \subseteq \mathcal{F}_2$ . It is easy to verify that  $\mathcal{F}_2$  is a  $\sigma$ -field.
- In general,  $\mathcal{F}_i = \{S\{0, 1\}^{n-k} : S \subseteq \{\omega_1 \dots \omega_k : \omega_i \in \{0, 1\}, \text{ for all } i \in \{1, \dots, k\}\}\}$ .

# Smallest Set Containing an Element

- Let  $x \in \Omega$
- Consider a  $\sigma$ -field  $\mathcal{F}$  on  $\Omega$
- The *smallest set in  $\mathcal{F}$  containing  $x$*  is the intersection of all sets in  $\mathcal{F}$  that contain  $x$ . Formally, it is the following set

$$\mathcal{F}(x) = \bigcap_{\substack{S \in \mathcal{F} \\ x \in S}} S$$

- For example, let  $n = 5$ ,  $x = 01001$  and consider the  $\sigma$ -field  $\mathcal{F}_2$  on  $\Omega$ . In this case, the smallest set  $\mathcal{F}_2(x)$  in  $\mathcal{F}_2$  containing  $x$  is  $01\{0, 1\}^{n-2}$

- Let  $f: \Omega \rightarrow \mathbb{R}$  be a function

## Definition ( $\mathcal{F}$ -Measurable)

The function  $f$  is  $\mathcal{F}$ -measurable if, for all  $y \in \mathcal{F}(x)$ , we have  $f(x) = f(y)$ , where  $\mathcal{F}(x)$  is the smallest subset in  $\mathcal{F}$  containing  $x$ .

- For example, let  $n = 5$  and consider the  $\sigma$ -field  $\mathcal{F}_2$  on  $\Omega$
- As we had seen, we have  $\mathcal{F}_2(x) = x_1 x_2 \{0, 1\}^{n-2}$ , where  $x_1$  and  $x_2$  are, respectively, the first and second bit of  $x$
- Let  $f(x)$  be the total number of 1s in the first two coordinates of  $x$ . This function is  $\mathcal{F}_2$ -measurable
- Let  $f(x)$  be the expected value of 1s over all strings whose first two bits are  $x_1 x_2$ . This function is  $\mathcal{F}_2$ -measurable
- Let  $f(x)$  be the total number of 1s in the first three coordinates of  $x$ . This function is *not*  $\mathcal{F}_2$ -measurable

# Conditional Expectation

- Let  $p$  be a probability distribution over the sample space  $\Omega$
- Let  $\mathcal{F}$  be a  $\sigma$ -field on  $\Omega$
- Let  $f: \Omega \rightarrow \mathbb{R}$  be a function
- We define the conditional expectation as a function  $\mathbb{E}[f|\mathcal{F}]: \Omega \rightarrow \mathbb{R}$  defined as follows

$$\mathbb{E}[f|\mathcal{F}](x) := \frac{1}{\sum_{y \in \mathcal{F}(x)} p(y)} \sum_{y \in \mathcal{F}(x)} f(y)p(y)$$

- We emphasize that  $f$  need not be  $\mathcal{F}$ -measurable to define the expectation in this manner!
- Note that  $\mathbb{E}[f|\mathcal{F}](x) = \mathbb{E}[f|\mathcal{F}](y)$ , for all  $y \in \mathcal{F}(x)$



- Let  $\Omega$  be a sample space with probability distribution  $p$

## Definition (Filtration)

A sequence of  $\sigma$ -fields  $\mathcal{F}_0, \mathcal{F}_1, \dots, \mathcal{F}_n$  is a *filtration* if  $\{\emptyset, \Omega\} = \mathcal{F}_0 \subseteq \mathcal{F}_1 \subseteq \dots \subseteq \mathcal{F}_n$ .

# Intuition Slides

# Sample Space

- 1 As time progresses, new information is revealed to us
- 2 At time 1, we learn the value  $\omega_1$  of the random variable  $\mathbb{X}_1$
- 3 At time 2, we learn the value  $\omega_2$  of the random variable  $\mathbb{X}_2$
- 4 And so on. At time  $t$ , we learn the value  $\omega_t$  of the random variable  $\mathbb{X}_t$
- 5 By the end of time  $n$ , we know the value  $\omega_n$  of the last random variable  $\mathbb{X}_n$
- 6 At this point of time,  $f(\mathbb{X}_1, \dots, \mathbb{X}_n)$  can be calculated, where  $f$  is a function that we are interested in

# Examples

- Balls and Bins. At time  $i$  we find out the bin  $\omega_i$  that the ball  $i$  goes into.
- Coin tosses. At time  $i$  we find out the outcome  $\omega_i$  of the  $i$ -th coin toss.
- Hypergeometric Series. At time  $i$  we find out the color  $\omega_i$  of the  $i$ -th ball draw from the jar (where sampling is being carried out without replacement).
- Bounded Difference Function. At time  $i$  we find out the outcome  $\omega_i$  of the  $i$ -th variable of the function  $f$ .

- The filtration  $\mathcal{F}_k$  is the tuple of outcomes  $(\omega_1, \dots, \omega_k)$
- The filtration  $\mathcal{F}_0$  represents no outcome is known
- The filtration  $\mathcal{F}_n$  represents that all outcomes are known

# Tree Representation

- Think of a rooted tree
- For every internal node, the outgoing edges represent the various possible outcomes in the next time step
- Leaves represent that all outcomes are already known
- The sequence of outcomes  $(\omega_1, \dots, \omega_n)$  represents a root to leaf path
- The filtration  $\mathcal{F}_k$  corresponding to this path is the depth- $k$  node on this path

# Measurable with respect to a Filtration

- A random variable  $\mathbb{X}_k$  will be measurable with respect to a filtration  $\mathcal{F}_k$  if the value of  $\mathbb{X}_k$  depends only on  $(\omega_1, \dots, \omega_k)$

## Definition (Martingale Sequence)

Let  $\{\emptyset, \Omega\} = \mathcal{F}_0 \subseteq \mathcal{F}_1 \subseteq \dots \subseteq \mathcal{F}_n$  be a filtration. The sequence  $(\mathbb{X}_1, \dots, \mathbb{X}_n)$  forms a martingale with respect to this filtration if  $\mathbb{X}_i$  is  $\mathcal{F}_i$ -measurable, for  $1 \leq i \leq n$ , and

$$\mathbb{E} [\mathbb{X}_{t+1} | \mathcal{F}_t] = (\mathbb{X}_t | \mathcal{F}_t),$$

for  $0 \leq t < n$ .

- Note that given  $\mathcal{F}_t = (\omega_1, \dots, \omega_t)$ , the value of  $\mathbb{X}_t$  is fixed
- Note that given  $\mathcal{F}_t = (\omega_1, \dots, \omega_t)$ , the outcome of  $\mathbb{X}_{t+1}$  is not yet fixed and is a random



## Example

- Consider tossing a coin that gives heads with probability  $p$ , and tails with probability  $(1 - p)$ , independently  $n$  times
- $\mathcal{F}_t$  is the outcomes of the first  $t$  coin tosses
- Let  $S_t$  represent the number of heads in the first  $t$  coin tosses
- Note that  $S_t$  is fixed given  $\mathcal{F}_t$
- Note that  $(S_{t+1}|\mathcal{F}_t) = (S_t|\mathcal{F}_t) + 1$  with probability  $p$ , else  $(S_{t+1}|\mathcal{F}_t) = (S_t|\mathcal{F}_t)$  with probability  $(1 - p)$
- Therefore,  $\mathbb{E}[S_{t+1}|\mathcal{F}_t] = (S_t|\mathcal{F}_t) + p$
- So,  $S_t$  is not a martingale sequence with respect to the filtration  $\mathcal{F}_0 \subseteq \mathcal{F}_1 \subseteq \dots \subseteq \mathcal{F}_n$

# Example

- Consider the random variable  $\mathbb{T}_t = \mathbb{S}_t - tp$
- Note that  $\mathbb{T}_t$  is fixed given  $\mathcal{F}_t$
- Note that  $(\mathbb{T}_{t+1}|\mathcal{F}_t) = (\mathbb{S}_t|\mathcal{F}_t) + 1 - (t+1)p$  with probability  $p$ , and  $(\mathbb{T}_{t+1}|\mathcal{F}_t) = (\mathbb{S}_t|\mathcal{F}_t) - (t+1)p$  with probability  $(1-p)$
- Therefore,  $\mathbb{E}[\mathbb{T}_{t+1}|\mathcal{F}_t] = (\mathbb{S}_t|\mathcal{F}_t) + p - (t+1)p = (\mathbb{T}_t|\mathcal{F}_t)$
- So, the sequence  $(\mathbb{T}_0, \mathbb{T}_1, \dots, \mathbb{T}_n)$  is a martingale sequence with respect to the filtration  $\mathcal{F}_0 \subseteq \mathcal{F}_1 \subseteq \dots \subseteq \mathcal{F}_n$

## Example

- Let  $f$  be a function and  $\mathcal{F}_t$  is the filtration where the first  $t$  arguments to  $f$  have been fixed
- Let  $\mathbb{F}_t$  be the random variable

$$\mathbb{F}_t = \mathbb{E} [f(\omega_1, \dots, \omega_t, \mathbb{X}_{k+1}, \dots, \mathbb{X}_n)]$$

- Prove:  $(\mathbb{F}_0, \dots, \mathbb{F}_n)$  is a martingale with respect to the filtration  $\mathcal{F}_0 \subseteq \mathcal{F}_1 \subseteq \dots \subseteq \mathcal{F}_n$
- This martingale is called: Doob's Martingale

# Martingale Difference Sequence

- Let  $\mathcal{F}_0 \subseteq \mathcal{F}_1 \subseteq \dots \subseteq \mathcal{F}_n$  be a filtration
- Let  $(\mathbb{X}_0, \dots, \mathbb{X}_n)$  be a martingale sequence with respect to the filtration above
- Let  $\mathbb{Y}_0 := \mathbb{X}_0$ , and  $\mathbb{Y}_{t+1} = \mathbb{X}_{t+1} - \mathbb{X}_t$ , for  $0 \leq t < n$
- Intuition:  $\mathbb{Y}_{t+1}$  measures the increase in  $\mathbb{X}_{t+1}$  from  $\mathbb{X}_t$
- Note that  $\mathbb{E}[\mathbb{Y}_{t+1} | \mathcal{F}_t] = 0$

# Azuma's Inequality

## Theorem (Azuma's Inequality)

Suppose  $(\mathbb{Y}_0, \dots, \mathbb{Y}_n)$  be a martingale difference sequence with respect to the filtration  $\mathcal{F}_0 \subseteq \mathcal{F}_1 \subseteq \dots \subseteq \mathcal{F}_n$ . Suppose  $a_{t+1} \leq (\mathbb{Y}_{t+1} | \mathcal{F}_t) \leq b_{t+1}$ , for  $0 \leq t < n$ . Then

$$\mathbb{P} \left[ \sum_{i=1}^n \mathbb{Y}_i \geq t \right] \leq \exp \left( - \frac{2t^2}{\sum_{i=1}^n (b_i - a_i)^2} \right)$$

- We only show how to bound

$$\mathbb{E} \left[ \exp \left( h \sum_{i=1}^n \mathbb{Y}_i \right) \right]$$

- Rest of the proof is identical to Hoeffding's Bound

- We are interested in computing

$$\begin{aligned}\mathbb{E} \left[ \exp \left( h \sum_{i=1}^n \mathbb{Y}_i \right) \right] &= \mathbb{E} \left[ \exp \left( h \sum_{i=1}^{n-1} \mathbb{Y}_i \right) \exp (h\mathbb{Y}_n) \right] \\ &\leq \mathbb{E} \left[ \exp \left( h \sum_{i=1}^{n-1} \mathbb{Y}_i \right) \exp (p_n e^{a_n} + q_n e^{b_n}) \right]\end{aligned}$$

where,  $p_n + q_n = 1$  and  $p_n a_n + q_n b_n = 0$ .

- Inductively,

$$\mathbb{E} \left[ \exp \left( h \sum_{i=1}^n \mathbb{Y}_i \right) \right] \leq \prod_{i=1}^n (p_i e^{a_i} + q_i e^{b_i})$$

- Rest of the proof is identical to the Hoeffding Bound proof



# Difference from Hoeffding's Bound

- The distribution  $\mathbb{Y}_{t+1}$  can depend on the outcomes  $(\omega_1, \dots, \omega_t)$
- But the only restrictions are that  $\mathbb{E}[\mathbb{Y}_{t+1} | \mathcal{F}_t] = 0$  and the outcomes  $(\mathbb{Y}_{t+1} | \mathcal{F}_t)$  are in the range  $[a_{t+1}, b_{t+1}]$
- Prove: The Bounded Difference Inequality using Azuma's Inequality
- Prove: The concentration of the Hypergeometric Distribution using Azuma's Inequality